

# **Practical Concurrent and Parallel Programming 6**

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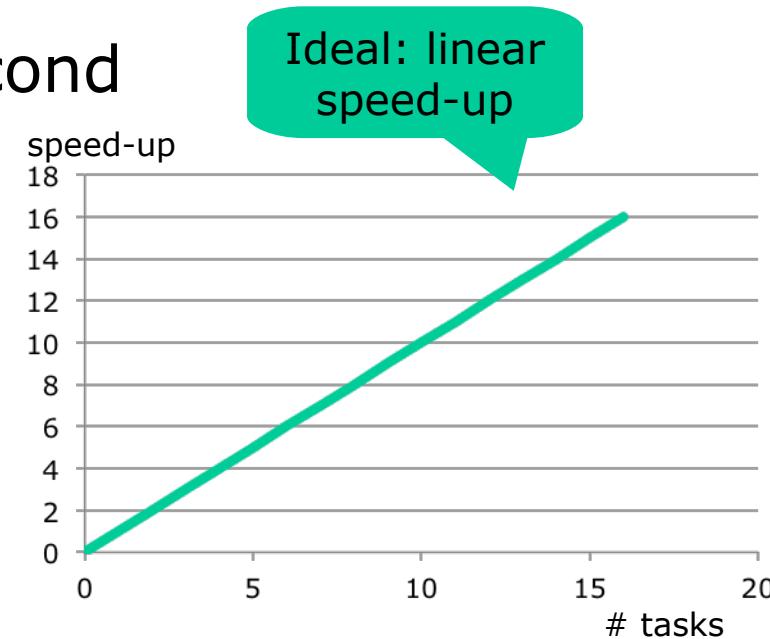
# Plan for today

- Performance and scalability
- Reduce lock duration by lock splitting
- Hash maps, a scalability case study
  - (A) Hash map à la Java monitor
  - (B) Hash map with lock striping
  - (C) Ditto with lock striping and non-blocking reads
  - (D) Java 8 library's ConcurrentHashMap

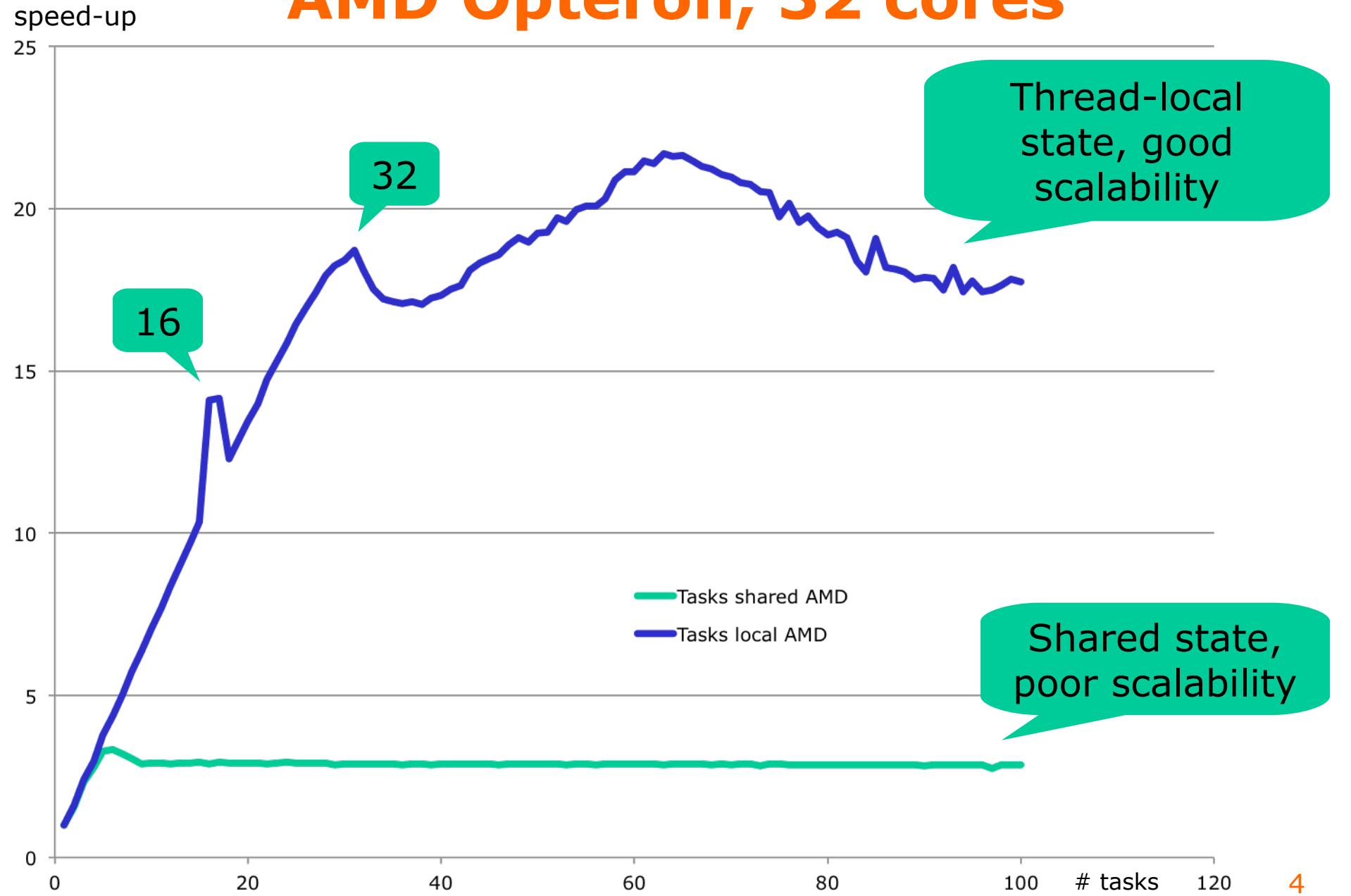
Based on slides by  
Peter Sestoft

# Performance versus scalability

- Performance
  - Latency: time till first result
  - Throughput: results per second
- Scalability
  - Improved throughput when more resources are added
  - Speed-up as function of number of threads or tasks
- One may sacrifice performance for scalability
  - OK to be slower on 1 core if faster on 2 or 4 or ...
  - Requires rethinking our “best” sequential code



# Scalability of prime counting AMD Opteron, 32 cores



# What limits throughput?

- CPU-bound
  - Eg. counting prime numbers
  - To speed up, add more CPUs (cores)
- Memory-bound
  - Eg. make color histograms of images
  - To speed up, improve data locality; recompute more
- Input/output-bound
  - Eg. fetching webpages and finding links
  - To speed up, use more tasks
- Synchronization-bound
  - Eg. image segmentation using shared data structure
  - To speed up, improve shared data structure. How?

Much of  
this lecture

# What limits scalability?

- Sequentiality of *problem*
  - Example: growing a crop
    - 4 months growth + 1 month harvest if done by 1 person
    - Growth (sequential) cannot be speeded up
    - Using 30 people to harvest, takes  $1/30$  month = 1 day
    - Maximal speed-up factor, using many many harvesters:  
 $5/(4+1/30) = 1.24$  times faster
  - Amdahl's law
    - $F$  = sequential fraction of problem =  $4/5 = 0.8$
    - $N$  = number of parallel resources = 30
    - Speed-up  $\leq 1/(F+(1-F)/N) = 1/(0.8+0.2/30) = 1.24$
- Sequentiality of *solution*
  - Solution slower than necessary because shared resources, eg. locking, sequentialize solution

# Reduce lock duration

Goetz p. 233-234

```
public class AttributeStore {  
    private final Map<String, String> attributes = ....;  
    public synchronized boolean userLocationMatches(String name,  
                                                   String regexp)  
    {  
        String key = "users." + name + ".location";  
        String location = attributes.get(key);  
        return location != null && Pattern.matches(regexp, location);  
    }  
}
```

Must lock

May be slow, holds  
lock unnecessarily

- Better:

```
public class BetterAttributeStore {  
    private final Map<String, String> attributes = ....;  
    public boolean userLocationMatches(String name, String regexp) {  
        String key = "users." + name + ".location";  
        String location;  
        synchronized (this) {  
            location = attributes.get(key);  
        }  
        return location != null && Pattern.matches(regexp, location);  
    }  
}
```

Lock only  
here

Does not hold lock

# Lock splitting

```
public class ServerStatusBeforeSplit {  
    @GuardedBy("this") public final Set<String> users = ...;  
    @GuardedBy("this") public final Set<String> queries = ...;  
    public synchronized void addUser(String u) {  
        users.add(u);  
    }  
    public synchronized void addQuery(String q) {  
        queries.add(q);  
    }  
    public synchronized void removeUser(String u) { . . .  
}
```

Lock server status object

Lock server status object

- Better, (addUser and addQuery can run concurrently)

```
public class ServerStatusAfterSplit {  
    @GuardedBy("users") public final Set<String> users = ...;  
    @GuardedBy("queries") public final Set<String> queries = ...;  
    public void addUser(String u) {  
        synchronized (users) { users.add(u); }  
    }  
    public void addQuery(String q) {  
        synchronized (queries) { queries.add(q); }  
    }  
    ...  
}
```

Lock only users set

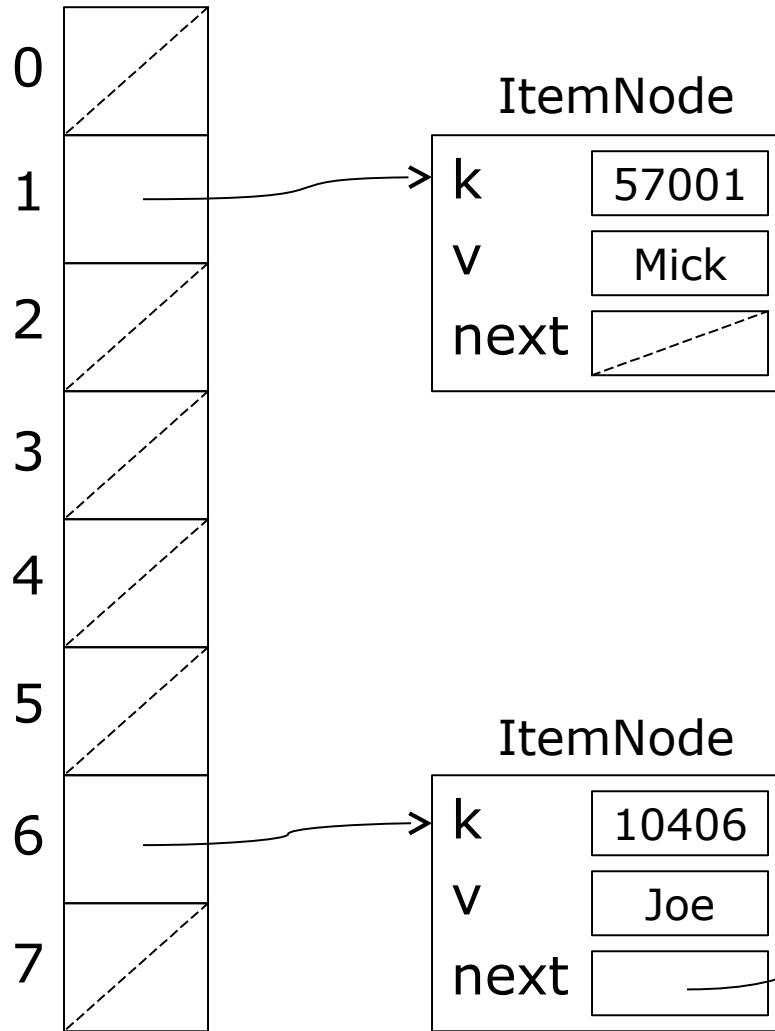
Lock only queries set

# Plan for today

- Performance and scalability
- Reduce lock duration, use lock splitting
- **Hash maps, a scalability case study**
  - (A) Hash map à la Java monitor
  - (B) Hash map with lock striping
  - (C) Ditto with lock striping and non-blocking reads

# A hash map = buckets table + item node lists

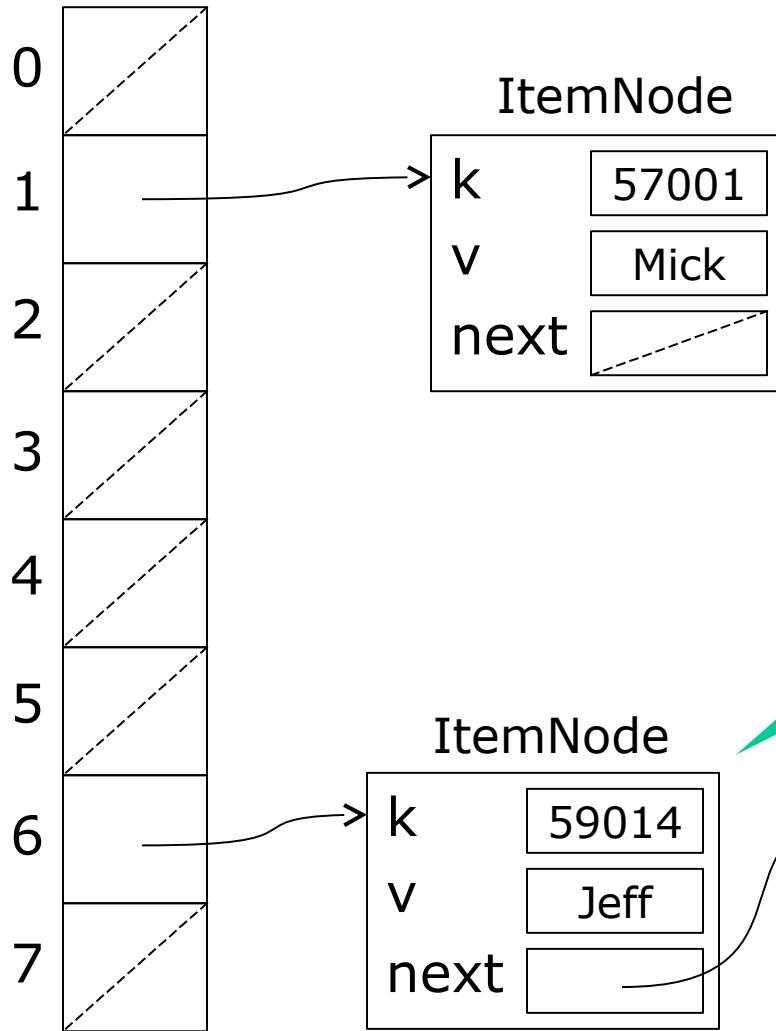
buckets



Example get (10406)  
key k is 10406  
k.hashCode() is 406  
bucket 406 % 8 is 6

# Insertion into the hashmap

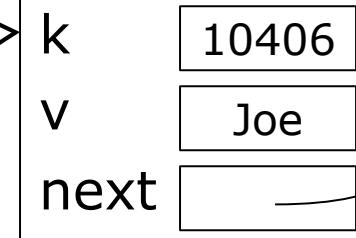
buckets



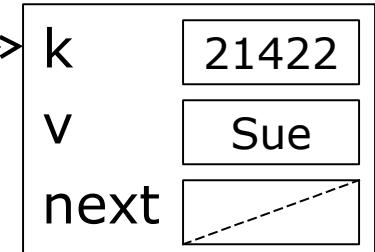
```
put(59014, "Jeff")  
key k is 59014  
k.hashCode() is 14  
bucket 14 % 8 is 6
```

New item

ItemNode

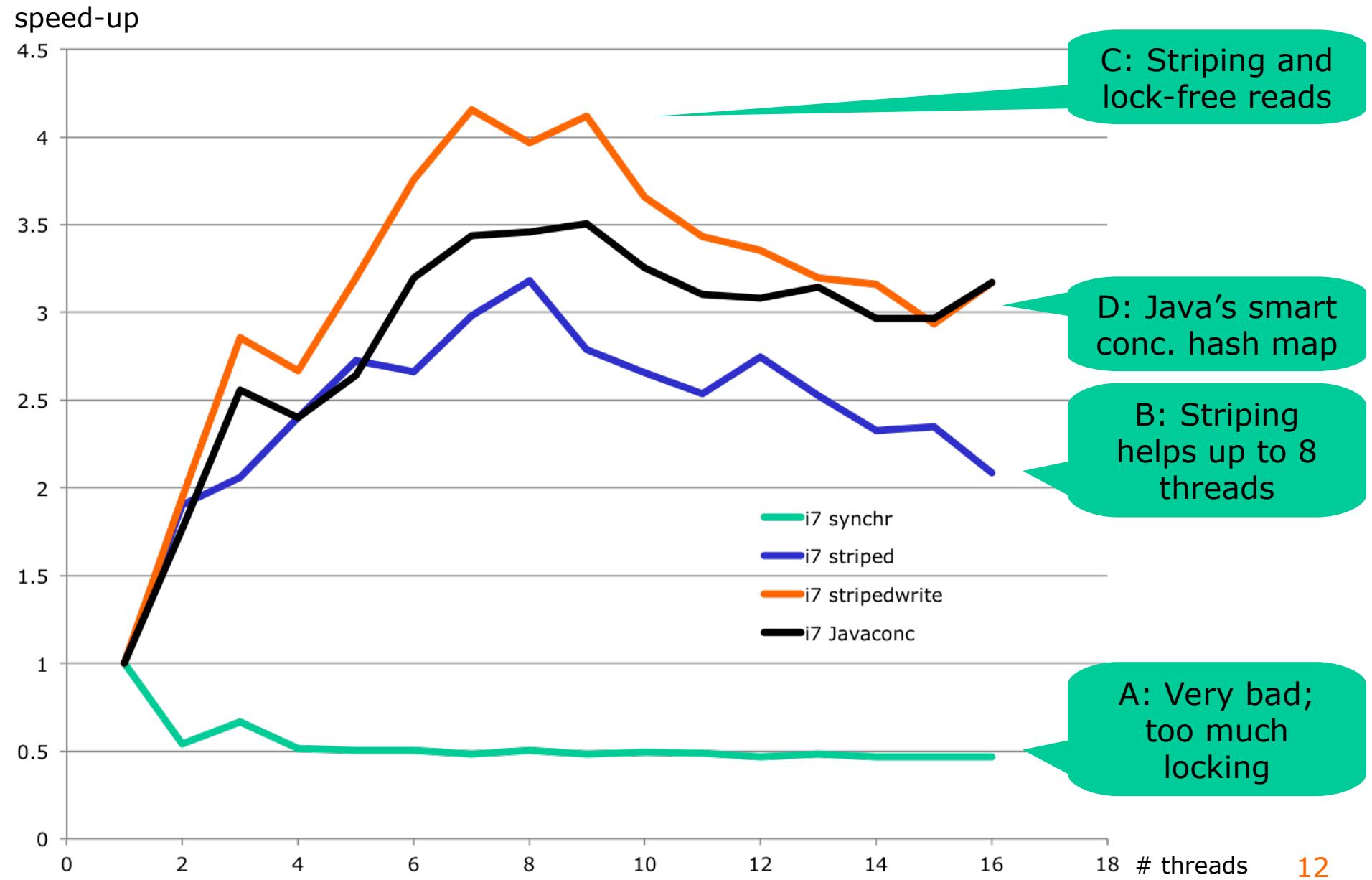


ItemNode



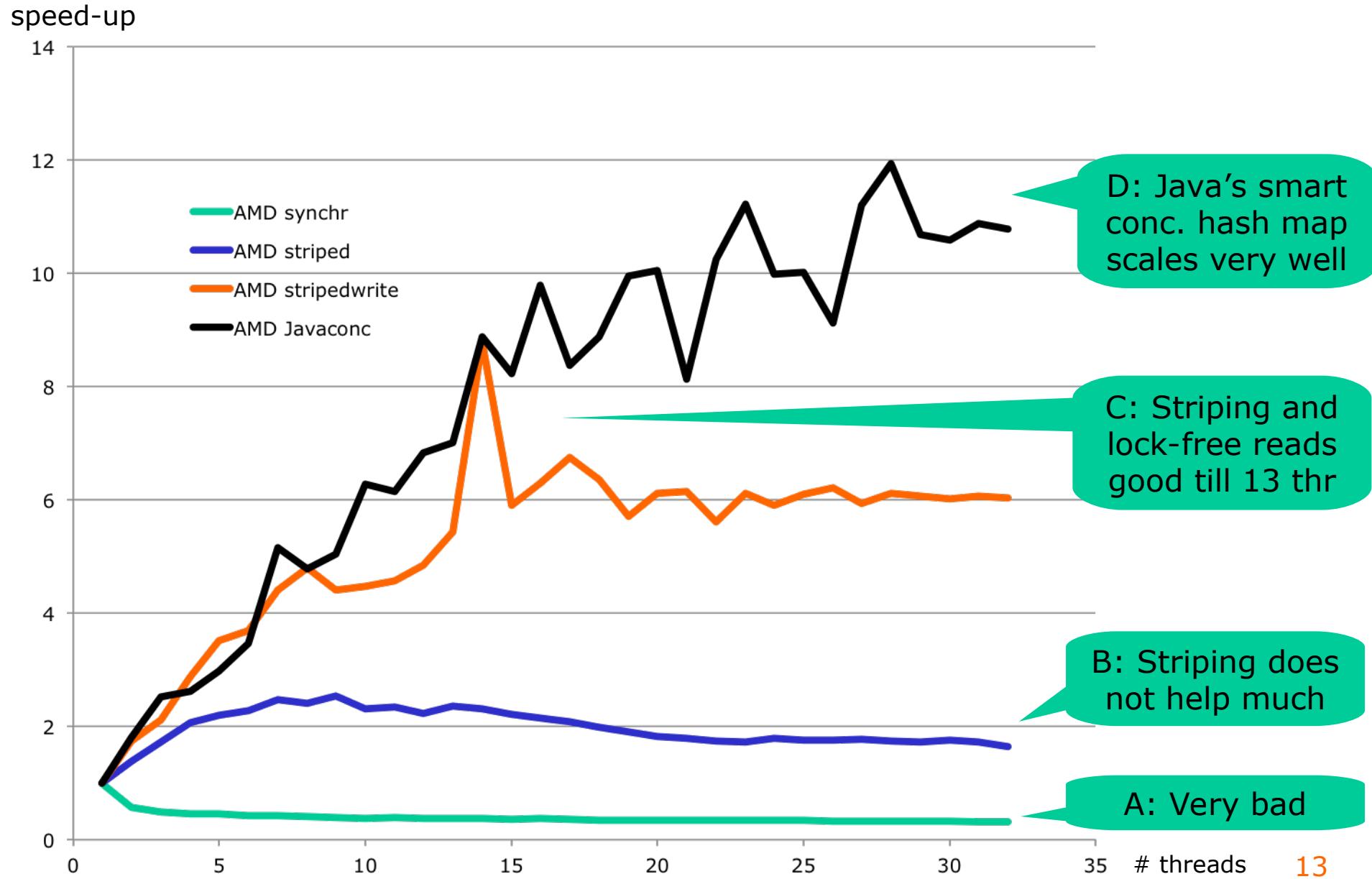
# Scalability of hash maps

## Intel i7 w 4 cores & hyperthreading



# Scalability of hash maps

## AMD Opteron w 32 cores



# Our map interface

- Reduced version of Java interface Map<K,V>

```
interface OurMap<K,V> {  
    boolean containsKey(K k);  
    V get(K k);  
    V put(K k, V v);  
    V putIfAbsent(K k, V v);  
    V remove(K k);  
    int size();  
    void forEach(Consumer<K,V> consumer);  
    void reallocateBuckets();  
}
```

```
interface Consumer<K,V> {  
    void accept(K k, V v);  
}
```

```
map.forEach((k, v) ->  
    System.out.printf("%10d maps to %s%n", k, v));
```

```
for (Entry (k,v) : map)  
    System.out.printf(...);
```

# Synchronized map implementation

```
static class ItemNode<K,V> {
    private final K k;
    private V v;
    private ItemNode<K,V> next; }.
    public ItemNode(K k, V v, ItemNode<K,V> next) { ... }
}
```

Visibility depends  
on  
synchronization

Java monitor  
pattern

```
class SynchronizedMap<K,V> implements OurMap<K,V> {
    private ItemNode<K,V>[] buckets; // guarded by this
    private int cachedSize;           // guarded by this
    public synchronized V get(K k) { ... }
    public synchronized boolean containsKey(K k) { ... }
    public synchronized int size() { return cachedSize; }
    public synchronized V put(K k, V v) { ... }
    public synchronized V putIfAbsent(K k, V v) { ... }
    public synchronized V remove(K k) { ... }
    public synchronized void forEach(Consumer<K,V> consumer) { ... }
}
```

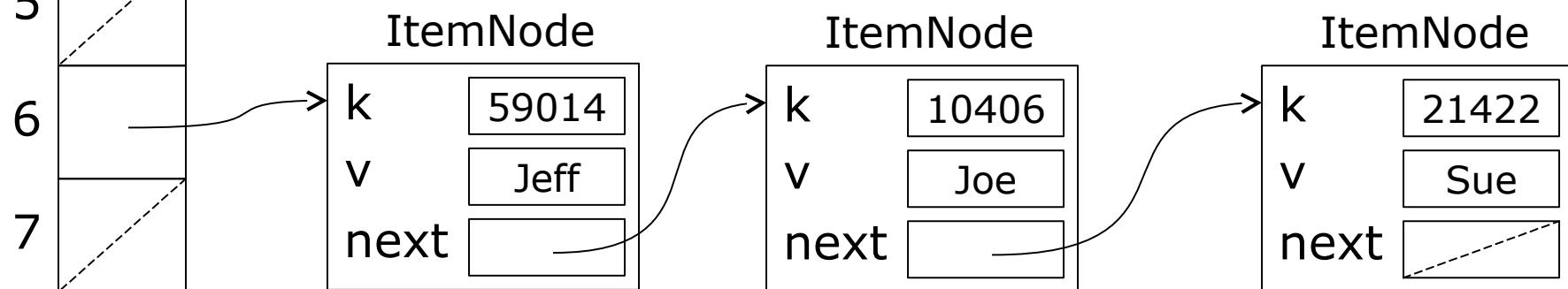
# Implementing containsKey

```
public synchronized boolean containsKey(K k) {
    final int h = getHash(k), hash = h % buckets.length;
    return ItemNode.search(buckets[hash], k) != null;
}
```

Find bucket

```
static <K,V> ItemNode<K,V> search(ItemNode<K,V> node, K k) {
    while (node != null && !k.equals(node.k))
        node = node.next;
    return node;
}
```

Search item  
node list



# Implementing putIfAbsent

```

public synchronized V putIfAbsent(K k, V v) {
    final int h = getHash(k), hash = h % buckets.length;
    ItemNode<K,V> node = ItemNode.search(buckets[hash], k);
    if (node != null)
        return node.v;
    else {
        buckets[hash] = new ItemNode<K,V>(k, v, buckets[hash]);
        cachedSize++;
        return null;
    }
}

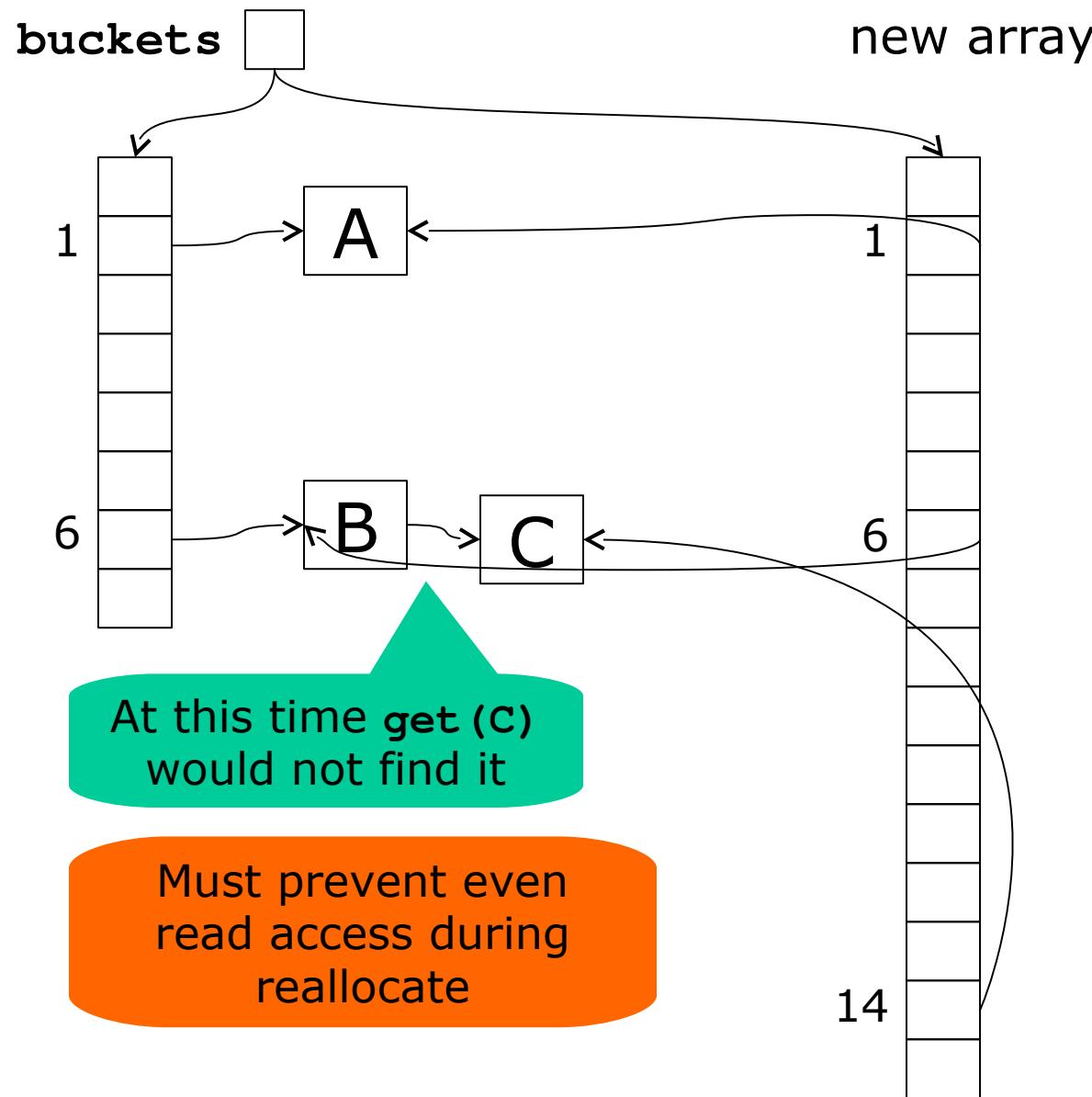
```

- All methods are synchronized
  - atomic access to buckets table and item nodes
  - all writes by put, putIfAbsent, remove, reallocateBuckets **are visible to** containsKey, get, size, forEach

# Reallocating buckets

- Hash map efficiency requires short node lists
- When item node lists become too long, then
  - Double buckets array size to newCount
  - For each item node (k,v)
    - Recompute `newHash = getHash(k) % newCount`
    - Link item node into new list at `newBuckets[newHash]`
- This is a dramatic operation
  - Must lock the entire data structure
  - Can happen at any insertion

# Double buckets array (mutating)



# ReallocateBuckets implementation

```

public synchronized void reallocateBuckets() {
    final ItemNode<K,V>[] newBuckets = makeBuckets(2 * buckets.length);
    for (int hash=0; hash<buckets.length; hash++) {
        ItemNode<K,V> node = buckets[hash];
        while (node != null) {
            final int newHash = getHash(node.k) % newBuckets.length;
            ItemNode<K,V> next = node.next;
            node.next = newBuckets[newHash];
            newBuckets[newHash] = node;
            node = next;
        }
    }
    buckets = newBuckets;
}

```

For each item node

Compute new hash  
Link into new bucket

- Seems efficient: reuses each ItemNode
  - Links it into a new item node list
  - So destroys the old item node list
  - So read access impossible during reallocation
  - Good 1-core performance, but bad scalability

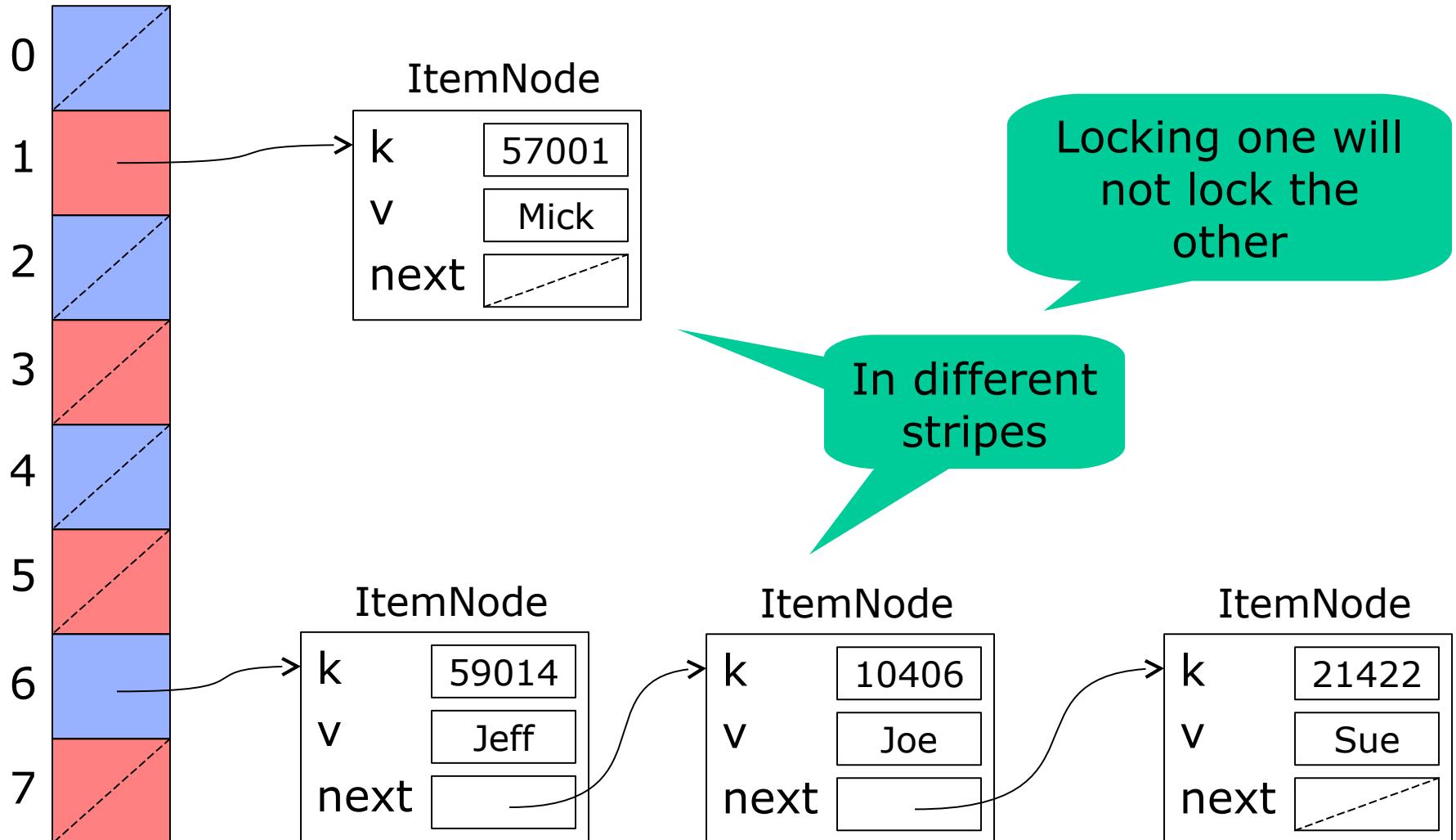
# Better scalability: Lock striping

- Guarding the table with a single lock works
  - ... but does not scale well (actually **very** badly)
- Idea: Each bucket could have its own lock
- In practice
  - use a few, maybe 16, locks
  - guard every 16<sup>th</sup> bucket with the same lock
  - locks[0] guards bucket 0, 16, 32, ...
  - locks[1] guards bucket 1, 17, 33, ...
- With high probability
  - two operations will work on different stripes
  - hence will take different locks
- Less lock contention, better scalability

# Lock striping in hash map

## Two stripes 0 = blue and 1 = red

buckets



# Striped hashmap implementation

NB!

```
class StripedMap<K,V> implements OurMap<K,V> {  
    private volatile ItemNode<K,V>[] buckets;  
    private final int lockCount;  
    private final Object[] locks;  
    private final int[] sizes;  
  
    public boolean containsKey(K k) { ... }  
    public V get(K k) { ... }  
    public int size() { ... }  
    public V put(K k, V v) { ... }  
    public V putIfAbsent(K k, V v) { ... }  
    public V remove(K k) { ... }  
    public void forEach(Consumer<K,V> consumer) { ... }  
}
```

Methods **not** synchronized

- Synchronization on **locks[stripe]** ensures
  - atomic access within each stripe
  - visibility of writes to readers

# Implementation of containsKey

```
public boolean containsKey(K k) {  
    final int h = getHash(k), stripe = h % lockCount;  
    synchronized (locks[stripe]) {  
        final int hash = h % buckets.length;  
        return ItemNode.search(buckets[hash], k) != null;  
    }  
}
```

- Compute key's hash code
- Lock the relevant stripe
- Compute hash index, access bucket
- Search node item list
- What if buckets were reallocated between computing **stripe** and locking?

# Representing hash map size

- Could use a single AtomicInteger **size**
  - might limit concurrency
- Instead use one **int** per stripe
  - read and write while holding the stripe's lock

```
public int size() {  
    int result = 0;  
    for (int stripe=0; stripe<lockCount; stripe++)  
        synchronized (locks[stripe]) {  
            result += sizes[stripe];  
        }  
    return result;  
}
```

- A stripe might be updated right after we read its size, before we return the sum
  - This is acceptable in concurrent data structures

# Striped put(k,v)

```
public V put(K k, V v) {  
    final int h = getHash(k), stripe = h % lockCount;  
    synchronized (locks[stripe]) {  
        final int hash = h % buckets.length; Lock stripe  
        final ItemNode<K,V> node = ItemNode.search(buckets[hash], k);  
        if (node != null) {  
            V old = node.v;  
            node.v = v; If k exists, update value to v, return old  
            return old;  
        } else {  
            buckets[hash] = new ItemNode<K,V>(k, v, buckets[hash]);  
            sizes[stripe]++; Else add new item node (k,v)  
            return null;  
        } And add 1 to stripe size  
    }  
}
```

# Reallocating buckets

- Must lock all stripes; how take **nlocks** locks?
  - Use recursion: each call takes one more lock

```
private void lockAllAndThen(Runnable action) {
    lockAllAndThen(0, action);
}

private void lockAllAndThen(int nextStripe, Runnable action) {
    if (nextStripe >= lockCount)
        action.run();
    else
        synchronized (locks[nextStripe]) {
            lockAllAndThen(nextStripe + 1, action);
        }
}
```

```
synchronized(locks[0]) {
    synchronized(locks[1]) {
        ...
        synchronized(locks[15]) {
            action.run();
        } ... } }
```

Overall effect of calling  
**lockAllAndThen (0, action)**

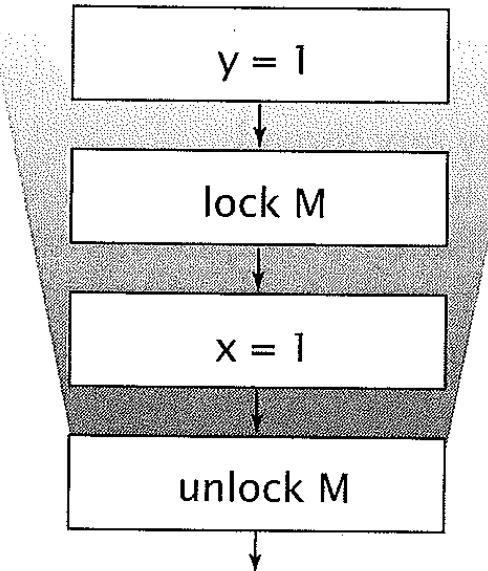
All locks held when  
calling **action.run ()**

# Idea: Immutable item nodes

- We can make read access lock free
- Good if more reads than writes
- A *read* of key k consists of
  - Compute `hash = getHash(k) % buckets.length`
  - Access `buckets[hash]` to get an item node list
  - Search the immutable item node list
- (1) Must make `buckets` access *atomic*
  - Get local reference:
- (2) No lock on reads, `final ImmutableList<ItemNode<K,V>> bs = buckets;`
  - Represent stripe sizes using AtomicIntegerArray
  - A hash map write must write to stripe size, **last**
  - A hash map read must read from stripe size, **first**
  - Also, declare `buckets` field **volatile**

# Visibility by lock, volatile, or atomic

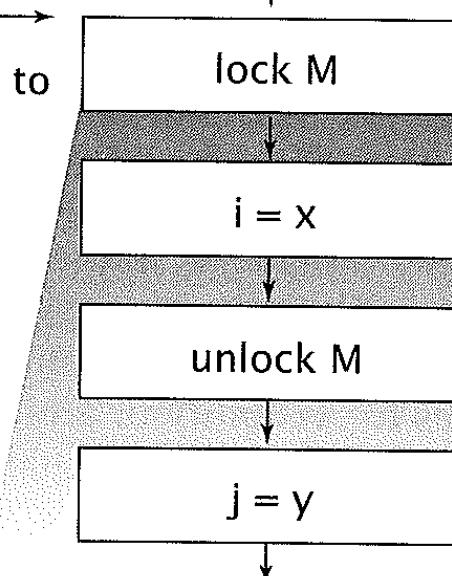
Thread A



... or before write to  
**volatile** or atomic

Everything  
before the  
unlock on M...

Thread B



... is visible to  
everything  
after the  
lock on M

... or after read from  
**volatile** or atomic

# Locking the stripes only on write

```
class StripedWriteMap<K,V> implements OurMap<K,V> {
    private volatile ItemNode<K,V>[] buckets;
    private final int lockCount;
    private final Object[] locks;
    private final AtomicIntegerArray sizes;
    ... non-synchronized methods, signatures as in StripedMap<K,V>
}
```

```
static class ItemNode<K,V> {
    private final K k;
    private final V v;
    private final ItemNode<K,V> next;

    static boolean search(ItemNode<K,V> node, K k, Holder<V> old) ...
    static ItemNode<K,V> delete(ItemNode<K,V> node, K k, Holder<V> old)
}

static class Holder<V> { // Not threadsafe
    private V value;
    public V get() { return value; }
    public void set(V value) { this.value = value; }
}
```

Immutable

To hold "out" parameters

# Lock-free containsKey

```
public boolean containsKey(K k) {
    final ItemNode<K,V>[] bs = buckets;
    final int h = getHash(k), stripe = h % lockCount,
        hash = h % bs.length;
    return sizes.get(stripe) != 0 && ItemNode.search(bs[hash], k, null);
}
```

Read volatile  
field, once ...

First read sizes, to make  
previous writes visible

... so that hash and  
array are consistent

- In class ItemNode, a plain linked list search:

```
static <K,V> boolean search(ItemNode<K,V> node, K k, Holder<V> old) {
    while (node != null)
        if (k.equals(node.k)) {
            if (old != null)
                old.set(node.v);
            return true;
        } else
            node = node.next;
    return false;
}
```

Item nodes are  
immutable and  
so threadsafe

If k found, may  
return v here

# Stripe-locking put(k,v)

```

public V put(K k, V v) {
    final int h = getHash(k), stripe = h % lockCount;
    synchronized (locks[stripe]) {
        final ItemNode<K,V>[] bs = buckets;
        final int hash = h % bs.length;
        final Holder<V> old = new Holder<V>();
        final ItemNode<K,V> node = bs[hash],
            newNode = ItemNode.delete(node, k, old);
        bs[hash] = new ItemNode<K,V>(k, v, newNode);
        sizes.getAndAdd(stripe, newNode == node ? 1 : 0);
        return old.get();
    }
}

```

Lock stripe

If k exists, delete, return (new) list

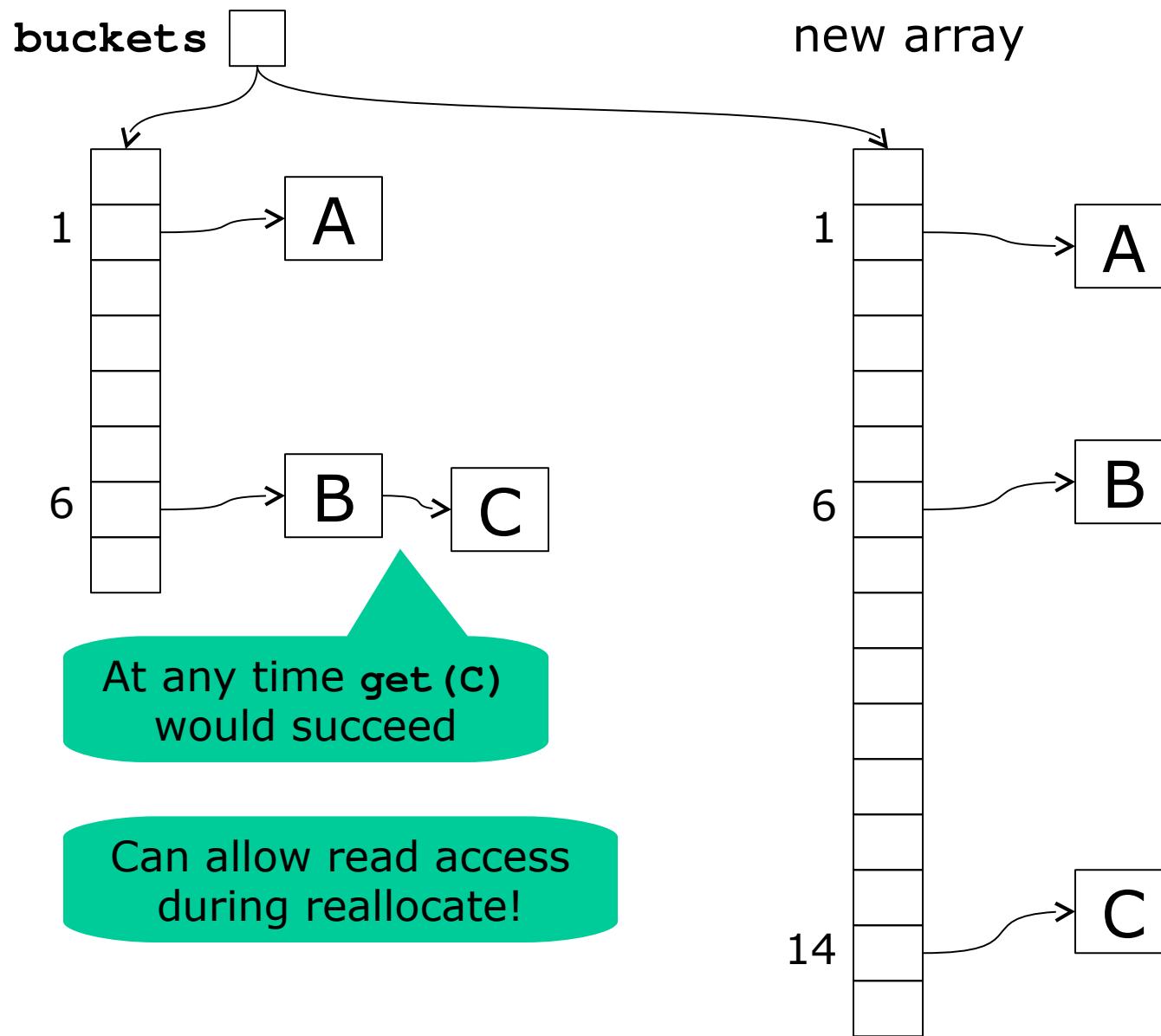
Add (k,v) to list

Add 1 to size if k wasn't already in

Else add 0 for visibility only

- To **put (k, v)**
  - Delete existing entry for **k**, if any
    - This may produce a new list of item nodes (immutable!)
  - Add new **(k, v)** entry at head of item node list
  - Update stripe size, *also* for visibility

# Double buckets array (non-mutating)



# StripedWriteMap in perspective

- StripedWriteMap design
  - incorporates ideas from Java's ConcurrentHashMap
  - yet is much simpler (Java's uses optimistic concurrency, compare-and-swap, week 10-11)
  - but also less scalable
- Is it correct?
  - I think so ...
  - Various early versions weren't 😞
- Can we test it?
  - Yes, week 8

# Comparison of concurrent hashmaps

	A	B	C	D
Concurrent reads	✗	✓	✓	✓
Concurrent reads and writes	✗	✓	✓	✓
Reads during reallocate	✗	✗	✓	?
Writes during reallocate	✗	✗	✗	?

- (A) Hash map à la Java monitor
- (B) Hash map with lock striping
- (C) Ditto with lock striping and non-blocking reads
- (D) Java 8 library's ConcurrentHashMap

# This week

- Reading
  - Goetz et al chapter 11, 13.5
- Exercises
  - Make sure you can write well-performing and scalable software using lock striping, immutability, Java atomics, and visibility rules; finish StripedMap and StripedWriteMap classes
- Read before next lecture (9 October)
  - Goetz et al chapter 9